

Discrete Fourier Transform (DFT)
&
Fast Fourier Transform (FFT)

Lab 9

Last Time

We found that an approximation to the Continuous Time Fourier Transform may be found by sampling $x(t)$ at every $m\Delta t$ and turning the continuous Fourier integral into a discrete sum.

$$X\left(k \frac{1}{N\Delta t}\right) \cong \Delta t \underbrace{\sum_{m=0}^{N-1} x(m\Delta t) e^{-j2\pi km/N}}_{\text{DFT}} = \Delta t \cdot \mathcal{DFT}(x(m\Delta t))$$

We gave this a name: Discrete Fourier Transform (DFT).

The DFT Pair



$$x[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k] e^{+j2\pi kn/N} \quad \xleftrightarrow{\mathcal{DFT}} \quad X[k] = \sum_{n=0}^{N-1} x[n] e^{-j2\pi kn/N}$$

These definitions assume that the first nonzero elements of $x[n]$ and $X[k]$ are $x[0]$ and $X[0]$!

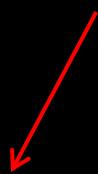
If your data (and program) do not follow this convention then there will be a phase shift in the forward DFT. A similar problem occurs for the reverse DFT.

For DFT $X[k]$ is periodic!

As it turns out $X[k]$ is periodic with period N regardless of the nature of $x[n]$!

$$x(t) \xleftrightarrow{\mathcal{F}} X(f) \qquad \delta_{T_0} \xleftrightarrow{\mathcal{F}} \frac{1}{T_0} \delta_{f_0}$$

Sampling a continuous-time signal is multiplying by a impulse train in the time domain. This of course has the result that the Fourier Transform is convolved with a impulse train resulting in shifted versions (periodic) in the frequency domain.

$$\therefore x(t) \cdot \delta_{T_0} \xleftrightarrow{\mathcal{F}} \frac{1}{T_0} \delta_{f_0} * X(f)$$


DFT is a misnomer!

It's actually equivalent to Discrete-Time Fourier Series.

DTFS

$$x[n] = \sum_{k=0}^{N-1} c_k[k] e^{j2\pi kn/N}$$

Discrete

CTFS

$$x(t) = \sum_{k=0}^{N-1} c_k[k] e^{j2\pi kn/N}$$

Continuous Discrete

=

Inverse DFT:

$$x[n] = \sum_{k=0}^{N-1} \frac{X[k]}{N} e^{j2\pi kn/N}$$

Why do we care?

MATH WORLD

CTFS

$$x(t) = \sum_{k=0}^{\infty} c_x[k] e^{j2\pi k/T}$$

$$c_x[k] = \frac{1}{T} \int_T x(t) e^{-j2\pi k/T} dt$$

Real WORLD (MATLAB)

(Approximate CTFS using DFT)

$$c_x[k] \cong \frac{1}{N} \cdot \mathcal{DFT}(x(n\Delta t))$$

You should care!

MATH WORLD

CTFT

$$x(t) = \int_{-\infty}^{\infty} X(f) e^{+j2\pi ft} df$$

$$X(f) = \int_{-\infty}^{\infty} x(t) e^{-j2\pi ft} dt$$

Real WORLD (MATLAB)

(Approximate CTFT using DFT)

$$X\left(\frac{k}{\Delta t N}\right) \cong \Delta t \cdot \mathcal{DFT}(x(n\Delta t))$$

$|k| \ll N$

Mindblown



MATH WORLD

DTFT

$$X(F) = \sum_{n=-\infty}^{\infty} x[n] e^{-j2\pi F n}$$

$$x[n] = \int_1 X(F) e^{j2\pi F n} dF$$

Real WORLD (MATLAB)

(Approximate DTFT using DFT)

$$F \rightarrow \frac{k}{N} \text{ and } 0 < n < N - 1$$

$$X\left(\frac{k}{N}\right) \cong \mathcal{DFT}(x[n])$$

$$x[n] \cong \frac{1}{N} \cdot \mathcal{DFT}^{-1}\left(X\left(\frac{k}{N}\right)\right)$$

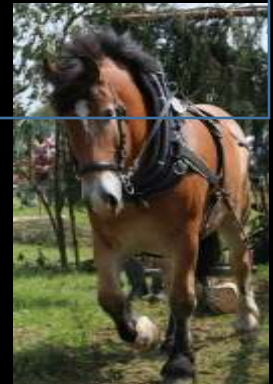
Fourier Family

Continuous Frequency, $X(f)$

Discrete Frequency, $X[k]$

Continuous Time, $x(t)$	Continuous Time Fourier Transform (CTFT)	Continuous Time Fourier Series (CTFS)
Discrete Time, $x[n]$	Discrete Time Fourier Transform (DTFT)	Discrete Time Fourier Series (DTFS) -OR- Discrete Fourier Transform (DFT)

DFT is the workhorse for Fourier Analysis in MATLAB!



DFT Implementation

Textbook's code pg. 303 is slow because of the awkward nested for-loops. The code we built in last lab is *much faster* because it has a single for-loop.

```
Elapsed time is 0.000466 seconds.  
Elapsed time is 0.073929 seconds.
```

Our code

Textbook's code

$$X[k] = \sum_{n=0}^{N-1} x[n] e^{-j2\pi kn/N}$$

Speed -FFT

“Uncle” Gauss



An DFT algorithm which decrease the number of computation (thereby decreasing the computation time) is called the **Fast Fourier Transform (FFT)**.

BUT!!!! It only is efficient when N is a integer power of two,

$N = \{1, 2, 4, 16, 32, 64, 128, 256, 512, 1024, \dots\}$

Otherwise there is no reduction in computation complexity!

fft() and ifft()

In MATLAB the FFT algorithm is already programmed in .

fft(x) operates on a vector x (in our case a discrete-time signal) and gives back the DFT of x . CAREFUL, It may need to be normalized!

Likewise **ifft(y)** operates on a vector y (in our case a discrete-frequency representation of a signal) and gives back the inverse DFT of y .

DFT Code to Approximate CTFT

```
deltat=0.01;           %time resolution
T=1.28;               %period
N=T/deltat;          %number of sample points
m=0:N;               %time index
a=-1j*2*pi/N;       %constant used below
xt=us(m*deltat).*exp(-m.*deltat); %time sampled signal
%preallocate frequency domain vector
Xf=zeros(1,N);
for k=0:N-1
    temp=xt.*exp(a*k.*m);
    Xf(k+1)=deltat*sum(temp);
end
stem(abs(Xf))
```

$$X\left(k\frac{1}{N\Delta t}\right) \cong \Delta t \cdot \mathcal{DFT}(x(m\Delta t))$$

FFT Code to Approximate CTFT

```
deltat=0.01;           %time resolution
T=1.28;               %period
N=T/deltat;          %number of sample points
m=0:N;               %time index
xt=us(m*deltat).*exp(-m.*deltat); %time sampled signal
Xf=deltat*fft(xt);   %FFT to compute CTFT approx.
stem(abs(y))
```

$$X\left(k\frac{1}{N\Delta t}\right) \cong \Delta t \cdot \mathcal{FFT}(x(m\Delta t))$$

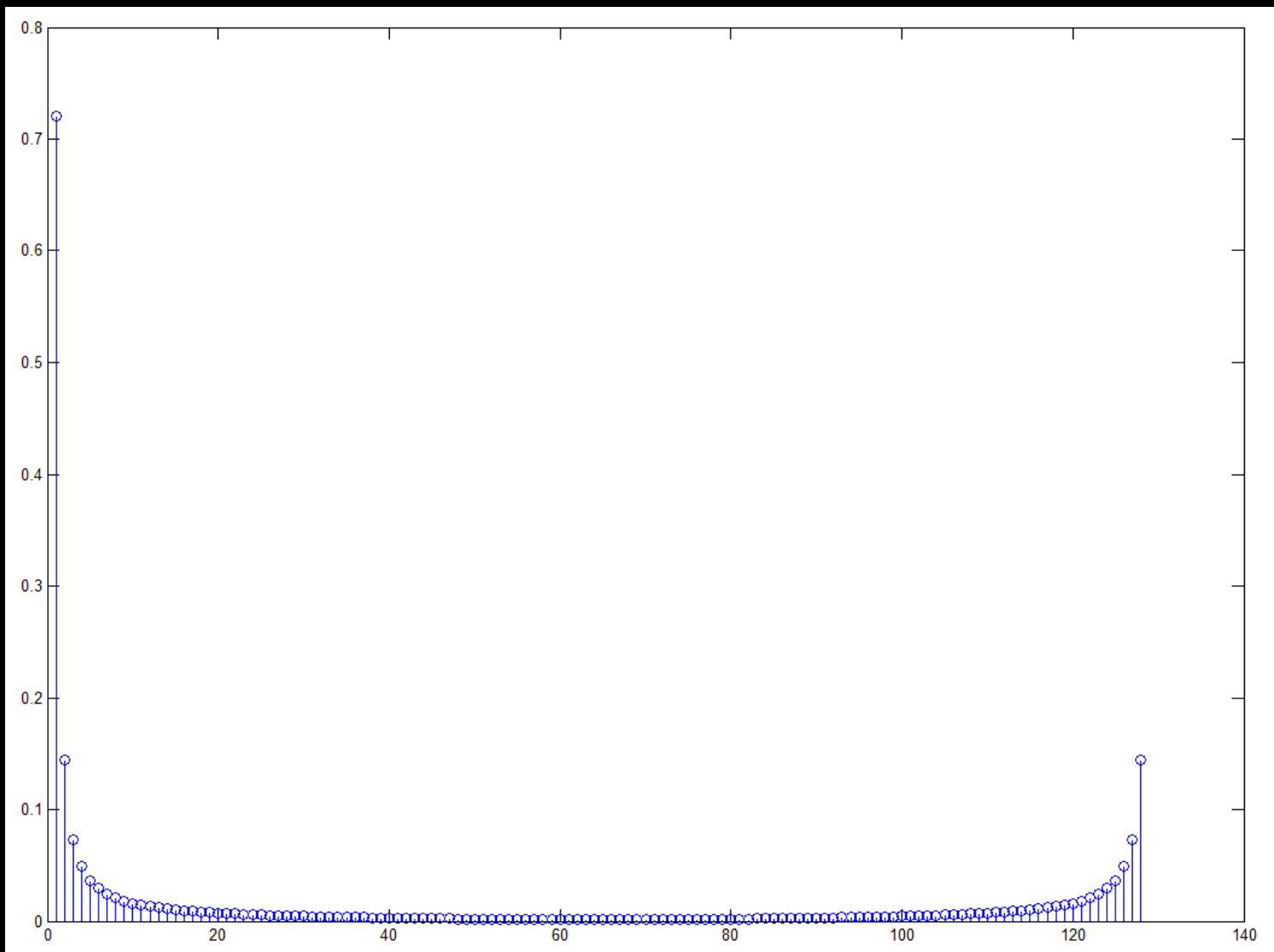
fftshift()

Remember I said $X[k]$ is periodic with period N ? We can use this to our advantage to plot the frequency “spectrum” by shifting the period to center around the DC component.

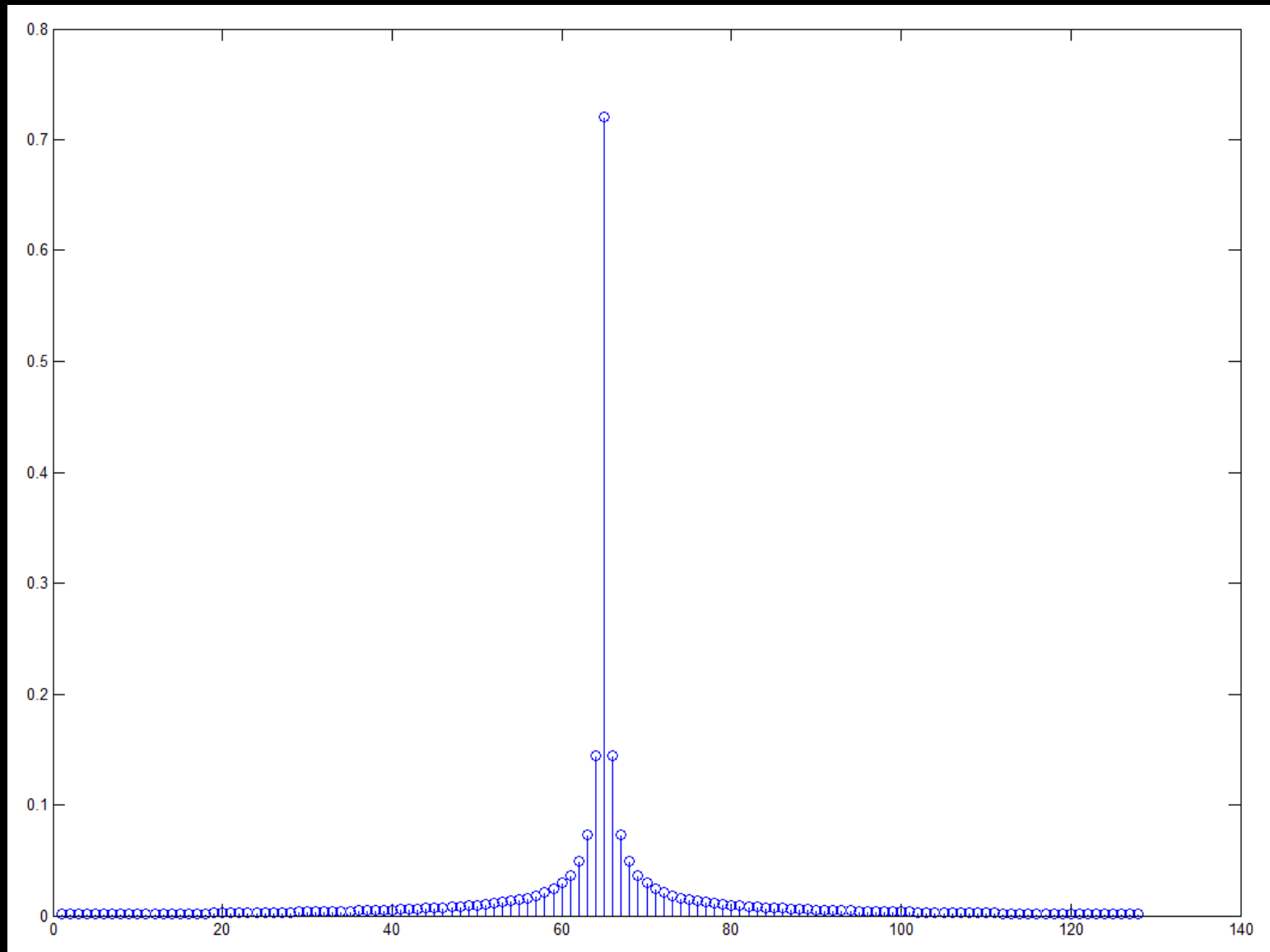
In MATLAB the function that does this is called `fftshift()`.

Note there is also a function `ifftshift()` which does the reverse.

Before `fftshift()`



After `fftshift()`



One last thought

When you use `fft()` you need to normalize the output.

In the case of the this lab where you are finding the DFT of a sampled rectangle function with amplitude one you should divide the result of `fft()` by N .

```
y=fft(x)/N;
```

$$\text{Parseval} \rightarrow \frac{1}{N} \sum_n^{\text{Period}} |x[n]|^2 = \frac{1}{N^2} \sum_k^{\text{Period}} |X[k]|^2$$