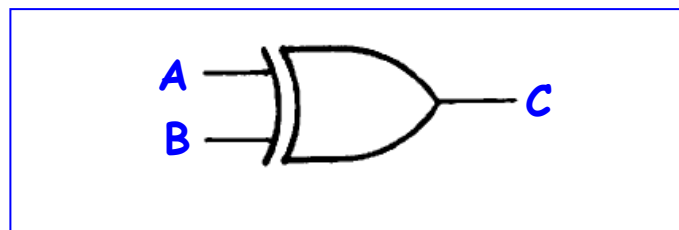


Ex-OR Phase Detectors

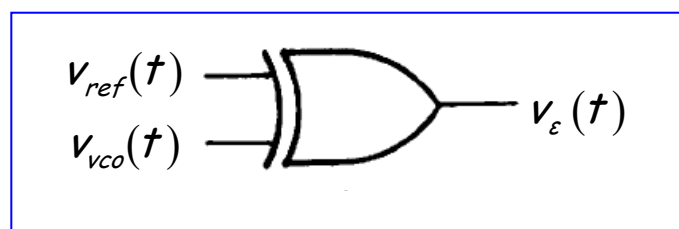
Consider an **exclusive-OR** gate. Recall the **truth table** for this gate is:

A	B	C
0	0	0
0	1	1
1	0	1
1	1	0

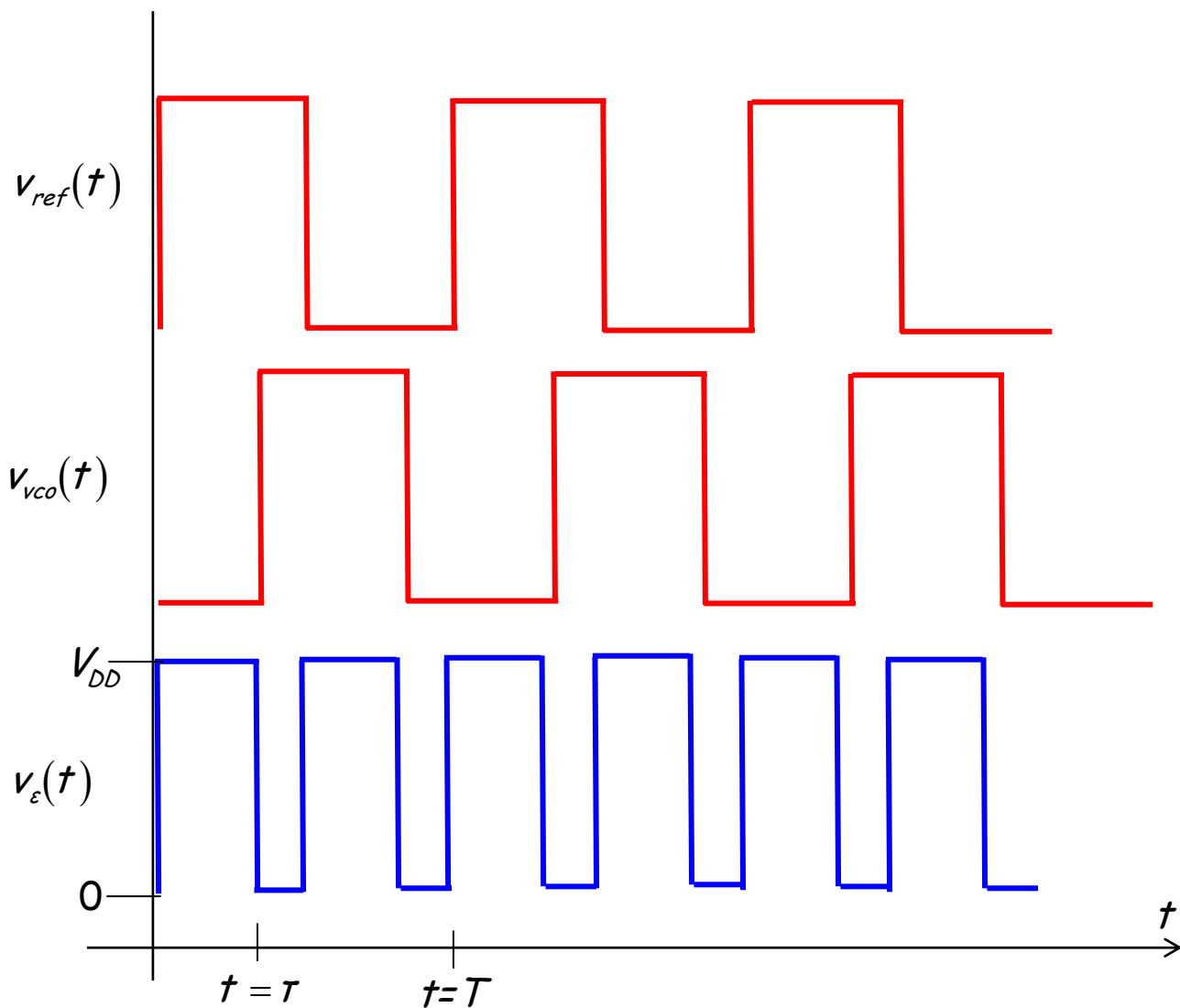


This device makes a great **phase detector** for **digital** signals of the form:

$$v(t) = \text{rect}[\theta(t)] \quad !!$$



A plot of these signals **could** be:



Q: Hey wait a minute! I thought you said that the **error** voltage was supposed to be **proportional** to the phase difference. This does not appear to be at all true.

A: It is true! It's just that the error voltage proportional to the phase difference is a little bit **hidden**.

Say we find the **time-averaged** value of error voltage $v_e(t)$ by integrating the error signal shown above over **one period**:

$$\frac{1}{T} \int_0^T v_{\varepsilon}(t) dt = 2V_{DD} \left(\frac{\tau}{T} \right)$$

This is of course the **DC component** of the error voltage (V_{ε}).

And **look** what it tells us!

The DC component of the error voltage provides us with the **delay** value τ/T —**this** is what we need to determine the phase difference!

Combining with the results above, we get:

$$V_{\varepsilon} = 2V_{DD} \left(\frac{\tau}{T} \right) = \left(\frac{V_{DD}}{\pi} \right) \Delta\theta$$

Thus, the **proportionality constant** for this phase detector is:

$$K_{\theta} = \left(\frac{V_{DD}}{\pi} \right)$$

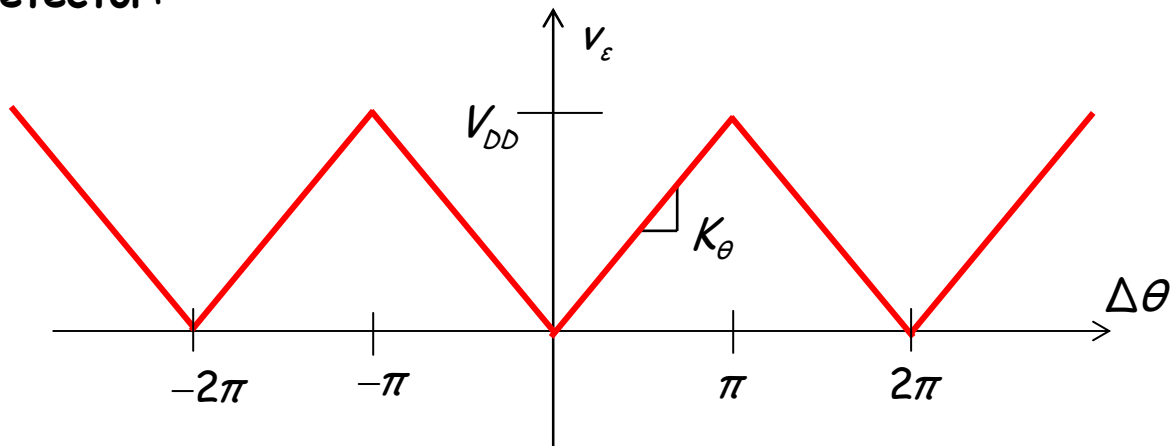
So that:

$$V_{\varepsilon} = K_{\theta} \Delta\theta$$

Q: *But wait! The error voltage likewise has a **AC component** (i.e., $v_{\varepsilon}(t) - V_{\varepsilon}$). Don't we have to **remove** this AC component?*

A: Absolutely! **How** can we remove the AC component from $v_{\varepsilon}(t)$??

Finally, we note that the Ex-OR phase detector is a π -phase detector:



Thus, its unambiguous detection range is **limited** to $0 \leq \Delta\theta \leq \pi$!