## **Projection Matrix Summary**

- 0. Recall, we build all 4x4 matrices here as a product:  $\mathbf{M}_{ec\text{-}lds} = \mathbf{M}_{wv} * \mathbf{M}_{proj}$  where:  $\mathbf{M}_{wv}$  does the window-viewport map into the -1..+1 logical device space of OpenGL  $\mathbf{M}_{proj}$  does the 3D to 2D projection with preservation of (at least relative) depth.
- 1. **Orthogonal** (<u>Given</u>: *x<sub>min</sub>*, *x<sub>max</sub>*, *y<sub>min</sub>*, *y<sub>max</sub>*, *z<sub>min</sub>*, *z<sub>max</sub>*, all specified in eye coordinates with *x<sub>min</sub><x<sub>max</sub>*; *y<sub>min</sub><y<sub>max</sub>*; and *z<sub>min</sub><z<sub>max</sub>*)

 $\mathbf{M}_{proj}$  is the identity matrix since there is nothing that needs to be done.  $\mathbf{M}_{wv}$  simply maps  $(x_{min}, x_{max}, y_{min}, y_{max}, z_{min}, z_{max})$  to (-1, 1, -1, 1, 1, -1). (Note the reversal in the *z* direction.)

This yields three pairs of equations with two unknowns:

$$a_{x}x_{min} + b_{x} = -1 \text{ and } a_{x}x_{max} + b_{x} = 1$$
$$a_{y}y_{min} + b_{y} = -1 \text{ and } a_{y}y_{max} + b_{y} = 1$$
$$a_{z}z_{min} + b_{z} = 1 \text{ and } a_{z}z_{max} + b_{z} = -1$$

Solving for  $a_x$ ,  $b_x$ ,  $a_y$ ,  $b_y$ ,  $a_z$ , and  $b_z$ , we get:

$$a_{x} = 2/(x_{\max} - x_{\min}); b_{x} = -(x_{\max} + x_{\min})/(x_{\max} - x_{\min})$$

$$a_{y} = 2/(y_{\max} - y_{\min}); b_{y} = -(y_{\max} + y_{\min})/(y_{\max} - y_{\min})$$

$$a_{z} = -2/(z_{\max} - z_{\min}); b_{z} = (z_{\max} + z_{\min})/(z_{\max} - z_{\min})$$
(1)

Hence

$$\mathbf{M}_{wv} = \begin{pmatrix} a_x & 0 & 0 & b_x \\ 0 & a_y & 0 & b_y \\ 0 & 0 & a_z & b_z \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

Finally,  $\mathbf{M}_{ec\text{-}lds} = \mathbf{M}_{wv}\mathbf{M}_{proj} = \mathbf{M}_{wv}\mathbf{I} = \mathbf{M}_{wv}$ .

**2. Oblique** (<u>Given</u>:  $z_{pp}$ ,  $x_{min}$ ,  $x_{max}$ ,  $y_{min}$ ,  $y_{max}$ ,  $z_{min}$ ,  $z_{max}$ , and  $\mathbf{d} = (d_x, d_y, d_z)$ , the common direction of projection, all specified in eye coordinates with  $x_{min} < x_{max}$ ;  $y_{min} < y_{max}$ ;  $z_{min} < z_{max}$ ; and  $d_z \neq 0$ )

 $\mathbf{M}_{proj}$  can be shown to be:

$$\mathbf{M}_{proj} = \begin{pmatrix} 1 & 0 & -d_x/d_z & z_{pp}d_x/d_z \\ 0 & 1 & -d_y/d_z & z_{pp}d_y/d_z \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

Clearly  $\mathbf{M}_{wv}$  is the same for oblique as for orthogonal, hence:

$$\mathbf{M}_{ec-lds} = \mathbf{M}_{wv} \mathbf{M}_{proj} = \begin{pmatrix} a_x & 0 & \frac{-a_x d_x}{d_z} & \frac{a_x z_{pp} d_x}{d_z} + b_x \\ 0 & a_y & \frac{-a_y d_y}{d_z} & \frac{a_y z_{pp} d_y}{d_z} + b_y \\ 0 & 0 & a_z & b_z \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

where  $a_x$ ,  $b_x$ ,  $a_y$ ,  $b_y$ ,  $a_z$ , and  $b_z$  are as given in equation (1) above.

**3. Perspective** (<u>Given</u>:  $z_{pp}$ ,  $x_{min}$ ,  $x_{max}$ ,  $y_{min}$ ,  $y_{max}$ ,  $z_{min}$ ,  $z_{max}$ , all specified in eye coordinates with  $x_{min} < x_{max}$ ;  $y_{min} < y_{max}$ ;  $z_{min} < z_{max} < 0$ ; and  $z_{pp} < 0$ )

We derive  $\mathbf{M}_{proj}$  (and, in particular, the portions of the transformation involving the eye coordinate *z* direction) so that mapping to the *z* range of LDS space is included in  $\mathbf{M}_{proj}$ . Thus we get:

$$\mathbf{M}_{wv} = \begin{pmatrix} a_x & 0 & 0 & b_x \\ 0 & a_y & 0 & b_y \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \qquad \mathbf{M}_{proj} = \begin{pmatrix} z_{pp} & 0 & 0 & 0 \\ 0 & z_{pp} & 0 & 0 \\ 0 & 0 & \alpha_z & \beta_z \\ 0 & 0 & 1 & 0 \end{pmatrix}$$

where  $a_x$ ,  $b_x$ ,  $a_y$ , and  $b_y$  are as given in equation (1) above. The  $\alpha_z$  and  $\beta_z$  terms can be shown to be:

$$\alpha_{z} = -\frac{z_{min} + z_{max}}{z_{max} - z_{min}}; \ \beta_{z} = \frac{2z_{min} z_{max}}{z_{max} - z_{min}}$$

Finally:

$$\mathbf{M}_{ec-lds} = \mathbf{M}_{wv} \mathbf{M}_{proj} = \begin{pmatrix} a_x & 0 & 0 & b_x \\ 0 & a_y & 0 & b_y \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} z_{pp} & 0 & 0 & 0 \\ 0 & z_{pp} & 0 & 0 \\ 0 & 0 & \alpha_z & \beta_z \\ 0 & 0 & 1 & 0 \end{pmatrix} = \begin{pmatrix} a_x z_{pp} & 0 & b_x & 0 \\ 0 & a_y z_{pp} & b_y & 0 \\ 0 & 0 & \alpha_z & \beta_z \\ 0 & 0 & 1 & 0 \end{pmatrix}$$

In principle, this matrix should be fine, but there is a clipping issue we will discuss that forces us to use the negated version of this matrix. Basically we need to be sure that the w component that results when this matrix is used is positive for any points in the view frustum. Since this matrix will set w=z, all visible points will have negative w. Negating the matrix prevents that without altering how points are projected since negating all 16 elements will just produce a different (but *projectively equivalent*) point. Hence:

$$\mathbf{M}_{ec-lds} = \begin{pmatrix} -a_x z_{pp} & 0 & -b_x & 0 \\ 0 & -a_y z_{pp} & -b_y & 0 \\ 0 & 0 & -\alpha_z & -\beta_z \\ 0 & 0 & -1 & 0 \end{pmatrix}$$

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